

## Warnings

- Connect the power supply and the display/output device according to the safety regulations for electrical equipment.
- > Risk of injury, damage to or destruction of the controller and/or the sensor
- Avoid shocks and impacts to the sensor and controller.
- > Damage to or destruction of the controller and/or the sensor
- The supply voltage must not exceed the specified limits.
- > Damage to or destruction of the controller and/or the sensor
- Protect the sensor cable against damage.
- > Destruction of the sensor, failure of the measuring device

## Notes on CE Marking

The following apply for the induSENSOR MSC7802:  
EU Directive 2014/30/EU and EU Directive 2011/65/EU, "RoHS"  
The sensor satisfies the requirements if the guidelines in the operating instructions are maintained in installation and operation.

## Proper Environment

- Temperature range:
  - Storage: -40 ... +85 °C (-40 ... +185 °F)
  - Operation: -40 ... +85 °C (-40 ... +185 °F)
- Humidity: 5 - 95% (non-condensing)
- Ambient pressure: Atmospheric pressure
- Protection class: IP 67
- Vibration/Shock: EN 60068-2

## Installation

- ➔ Fasten the controller of series MSC7802 by means of two M4 screws.
- The position of the mounting holes is shown in the drawing below. The tightening torque for the cover screws is 0.9 Nm. The maximum tightening torque for the SW15 (M12) cable gland is 1.5 Nm and for the SW19 (M16) cable gland is 3 Nm.
- Please note that less torque should be applied for cable glands with various cable sheath materials.
- > Damage to the cable sheath

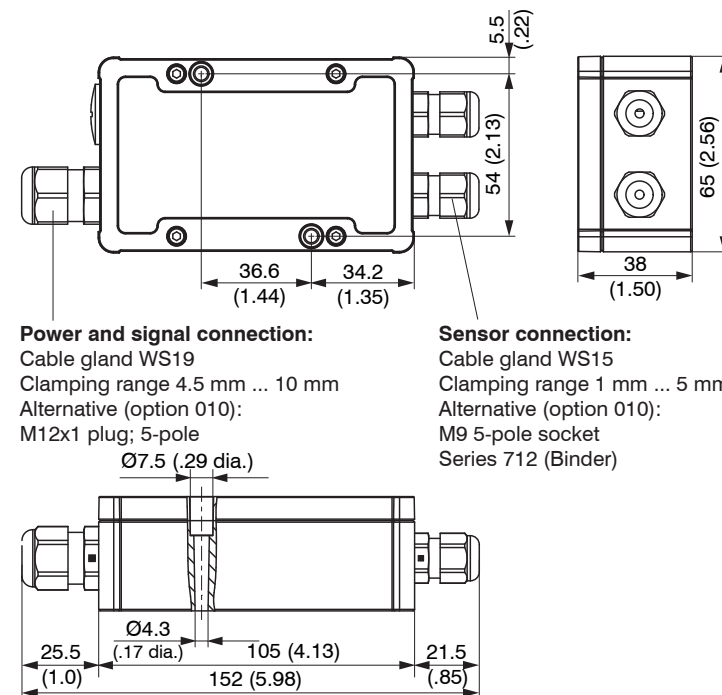


Fig. 1 Dimensions of MSC7802<sup>1</sup> controller, dimensions in mm, not to scale

1) Option MSC7802(010) has different dimensions.

Terminal block X2	Pin	Cable 1 LDR-x-CA LVP-25-20-x	Connector LDR-x-SA	Sensor cable 1 C7210-x
Shield (sensor cable)	1	-	-	-
Secondary center tap	2	Green	4	Black
Secondary +	3	White	1	Brown
Secondary -	4	Brown	3	Blue
Primary +	5	-	-	-
Primary -	6	-	-	-

Fig. 4 Table of the pin assignment for the sensor at terminal block X2, half bridge

1) The colors and pins listed refer to the sensors from MICRO-EPSILON MESSTECHNIK GmbH & Co. KG.

The pin assignment for the terminal blocks can also be found in the following table.

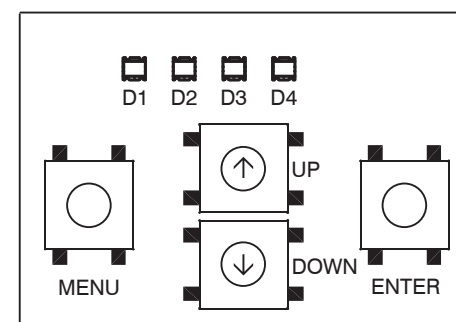
More information and graphics can be found in the operating instructions, Chap. 4.4.

Instructions on operation can be found in the operating instructions starting at Chap. 5.3.

Pin	Terminal block X2: Sensor connection	Terminal block X3: Digital interface RS485	Terminal block X1: Supply and signal
1	Housing/shield	RS485 A	Analog output for channel 1
2	Secondary center tap	RS485 B	Analog output for channel 2
3	Secondary +	-	Supply voltage
4	Secondary -	-	GND supply/signal ground
5	Primary +	-	-
6	Primary -	-	Housing/shield

Fig. 5 Pin assignment for terminal blocks

## Control and Display Elements



Button/LED	Function	Description
Menu button	Enter the menu level	-
Enter button	Confirmation	-
↑ and ↓ buttons	Parameter selection	-
D1 LED	Channel display	The Channel LED indicates the current channel. Channel 1: green, channel 2: red It flashes in corresponding color, if the channel is not parameterized.
D2 LED	E1 menu level display	The E1 and E2 LEDs show the current position in the menu or the corresponding settings.
D3 LED	E2 menu level display	
D4 LED	Value display	The Value LED indicates the current value of the selected parameters.

## Setting

The controller can be easily set using buttons, LEDs or a software (see operating instructions, Chap. A3).

Sensor model	Measuring range	Sensor type	Supply frequency	Excitation voltage	
DTA-1x	±1 mm	LVDT	5 kHz	550 mV	
DTA-3x	±3 mm		5 kHz		
DTA-5x	±5 mm		5 kHz		
DTA-10x	±10 mm		2 kHz		
DTA-15x	±15 mm		1 kHz		
DTA-25x	±25 mm		1 kHz		
LDR-10	10 mm	LDR	21 kHz	550 mV	
LDR-25	25 mm		13 kHz		
LDR-50	50 mm		9 kHz		
LVP-3	3 mm		18 kHz		
LDR-14	With 8 mm drawbar		14 mm		23 kHz
	With 10 mm drawbar				23 kHz
LVP-25	With 8 mm drawbar	25 mm	16 kHz		
	With 10 mm drawbar		16 kHz		

Fig. 2 Sensor models and sensor parameters

You can download a PDF of detailed operating instructions from our website:  
<http://www.micro-epsilon.de/download/manuals/man--induSENSOR-MS7xxx--en.pdf>

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Assembly Instructions  
**induSENSOR**  
**MSC7802**

## Power Supply, Sensor and Signal Output

The minimum bending radius of the PC7400-6/4 and PC5/5-IWT power supply and output cables (available as accessories) is ten times the cable diameter. All of the connections for the power supply/sensors/signal output are on the controller.

## Connections

- Power supply/output side:
  - Cable gland: SW19; clamping range 4.5 mm ... 10 mm
  - Screw terminal connection; AWG 16 up to AWG 24; up to AWG 28 with ferrule
  - alternatively: Connector M12x1, 5-pole, A-coded
- Sensor side:
  - Cable gland: SW15; clamping range 1 mm ... 5 mm
  - Screw terminal connection; AWG 16 up to AWG 24; up to AWG 28 with ferrule
  - alternatively: female connector M9; 5-pole, series 712, Co. Binder

## Wiring

The housing must be open to connect the sensors and wire the output and power supply cable.

- ➔ Loosen the screws.
- ➔ Pass the sensor and signal cables through the cable glands.
- ➔ Connect the cables to the terminals according to the pin assignments.

Terminal block X2	Pin	Cable 1 DTA-x-CA-x DTA-x-CR-x C701-x	Braid 1 DTA-x- LA-x	Solder pin 1 DTA-x- TA-x	Cable 1 DTA-xG8-x
Shield (sensor cable)	1	Shield	-	-	Shield
Secondary center tap	2	Gray	Gray	5	Gray
Secondary +	3	White	White	1	Black
Secondary -	4	Brown	Black	2	White
Primary +	5	Green	Green	3	Blue
Primary -	6	Yellow	Yellow	4	Brown

Fig. 3 Table of the pin assignment for the sensor at terminal block X2, full bridge

## Pin assignment for power supply and signal

Pin	Description
1	Supply voltage
2	Analog output for channel 2
3	GND supply/signal ground
4	Analog output for channel 1
5	-

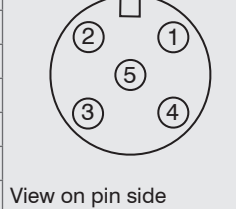


Fig. 6 Pin assignment for power supply and signal, 5-pin housing connector M12x1 (A-coded)

## Sensor pin assignment

Pin	Description
1	Secondary +
2	Secondary -
3	Primary +
4	Primary -
5	Secondary center tap

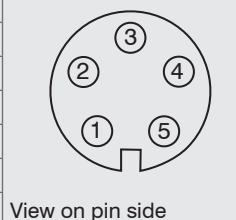
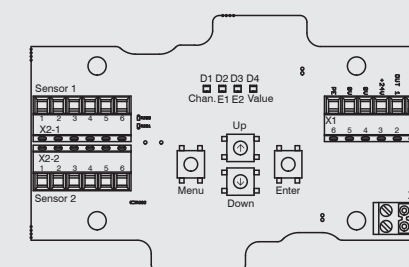


Fig. 7 Pin assignment for sensor, 5-pin housing socket M9 (Binder series 712)

## Initial Operation



- ➔ Connect the sensor before starting the controller.
- ➔ Ensure that the wiring of the sensor connections, signal cable and power supply connections are correct before connecting the controller to the power supply and turning it on.
- ➔ Then switch on the power supply.
- ➔ Set the controller to its basic setting.



## Menu Structure for the MSC7802 Controller

D1: <input type="checkbox"/> Channel	D2: <input type="checkbox"/> E1	D3: <input type="checkbox"/> E2	D4: <input type="checkbox"/> Value	Next menu
	Adjustment		2-point adjustment 	Go to the adjustment modes 2-point adjustment, see Fig. 8 or zero-point search, see Fig. 9.
			Factory settings 	
			Zero-Point Search	
		Automatic sensor recognition		Successful
				Failed
				Manually set
				Successful
				Failed
			<input type="checkbox"/>	Manually set
				Display only
				Automatic
				Voltage
				0 ... 10 V
				2 ... 10 V
				0 ... 5 V
				0.5 ... 4.5 V
				E1 level
				4 ... 20 mA
				0 ... 20 mA
				0 ... 10 mA
		Sensor parameter		DTA (LVDT)
			Sensor type	LDR
			Frequency	DTA
				LDR
				1 kHz
				9 kHz
				2 kHz
				13 kHz
				5 kHz
				16 kHz
				10 kHz
				21 kHz
				13 kHz
				23 kHz
			Amplitude	550 mV
				350 mV
				150 mV
				75 mV
				E1 level

### Legend of the Menu Structure

	LED orange		LED red
	LED orange flashing		LED red flashing
	LED green	<input type="checkbox"/>	LED off
	LED green flashing	SMR	Start of measuring range
		MMR	Mid of measuring range
		EMR	End of measuring range

## Menu Structure for the MSC7802 Controller, Adjustment Mode: 2-point Adjustment

D1: <input type="checkbox"/> Channel	D2: <input type="checkbox"/> E1	D3: <input type="checkbox"/> E2	D4: <input type="checkbox"/> Value
	Move the measuring object to position X1, and change the output signal U1 with		
			Flashes orange when the measuring object is in the electrical center of the sensor.
	Move the measuring object to position X2 1 and change the output signal U2 with		
			Flashes orange when the measuring object is in the electrical center of the sensor.

Fig. 8 Menu structure for the MSC7802 controller, adjustment mode: 2-point adjustment

1) Position X2 must be > 10% of the measuring range away from X1.

## Menu Structure for the MSC7802 Controller, Adjustment Mode: Zero-point Search

D1: <input type="checkbox"/> Channel	D2: <input type="checkbox"/> E1	D3: <input type="checkbox"/> E2	D4: <input type="checkbox"/> Value
	Set the output signal U0.		<input type="checkbox"/>
			LED off
	6 VDC or 12 mA is preset.		
	Move the measuring object to position X0 until the output has reached U0.		
		The LED flashes and color changes depending on the output signal (green = too low, red = too high).	Lights orange when the measuring object is in the electrical center of the sensor.
	Move the measuring object to position X2 1 and change the output signal U2 with		
			The LED color changes depending on the position of the measuring object.
			Flashes orange when the measuring object is in the electrical center of the sensor.

Fig. 9 Menu structure for the MSC7802 controller, adjustment mode: Zero-point search

1) Position X2 must be > 10% of the measuring range away from X1.